

10 - REAR GAUGE ASSEMBLIES

10 - 1 DESCRIPTION

Mechanical part of the back gauge assembly.

The mechanical part of the back gauge unit is made up of a compact assembly attached to the lower beam on the press. A DC motor (item 4) is attached to the rear of the compact assembly, and transmits movement via notched belts (item 5) to one (model 412) or two (model 600) ball screws.

The rotation of the ball screws moves the mobile crosspiece.

A group of casings (item 9) protect the mechanisms in the rear gauge assembly unit and provide operator safety.

Two proximity detectors (items 6 and 7) front and rear stop the movement at the end of the strokes.

Positioning of the sheet is regulated by the two slide runners (item 10) that are adjustable over the entire length of the slide guide plate (item 1). Each slide runner is fitted with stop finger articulated upward.

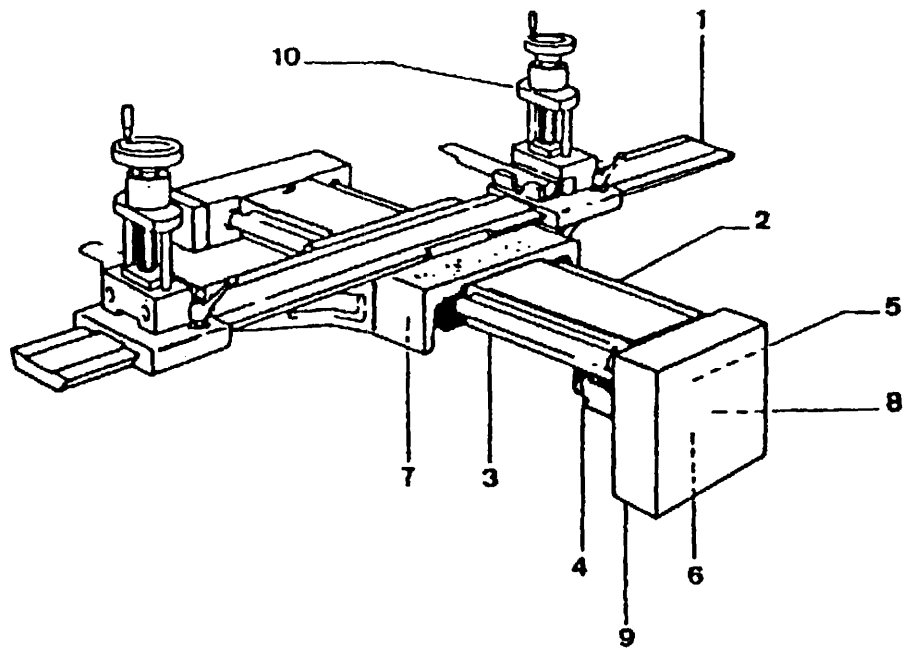
An encoder (item 8) coupled to the motor (item 4) generates counting and resetting signals.

Motor driver on stop fingers:

The mobile fingers are motor driven to provide programmed and automatic vertical movement for the stay following a predetermined sequence over the entire length of the stroke (150 mm).

Via a belt, a DC motor transmits movement to a threaded bolt (master bolt) which moves the stop finger. The end of the lower stroke is controlled by a proximity detector used to realign the assembly.

10 - 2 REAR GAUGE ASSEMBLY MECHANISM ON MODEL 412



1 - Slide guide plates

2 - Guide spindles

3 - Ball screw

4 - Motor

5 - Transmission system

6 - Inductive sensors

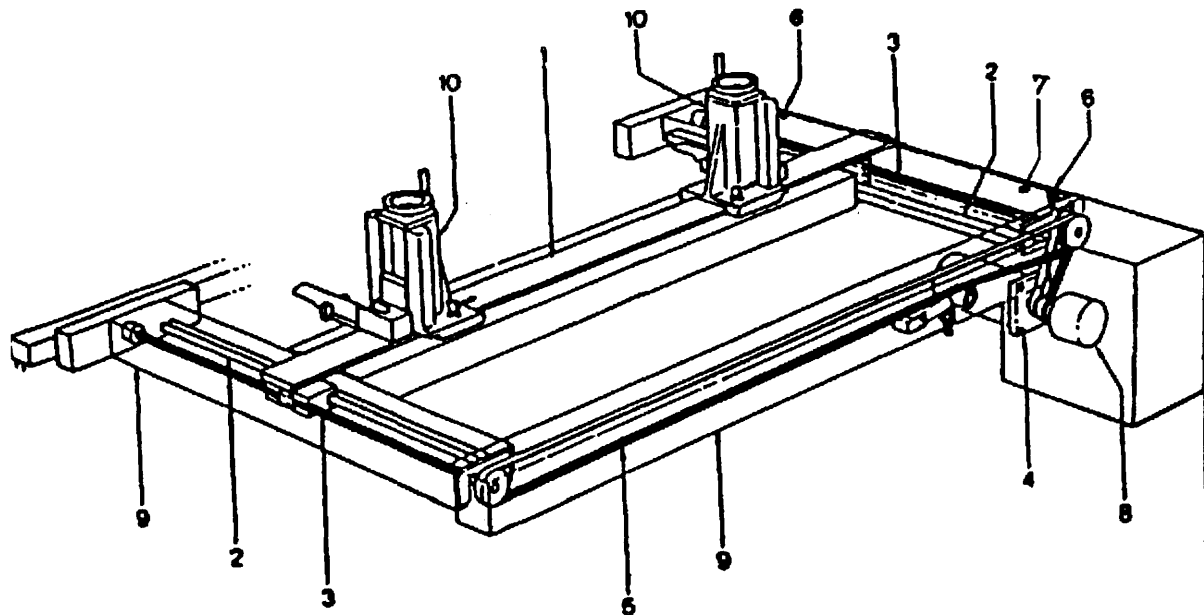
7 - Detector

8 - Encoder

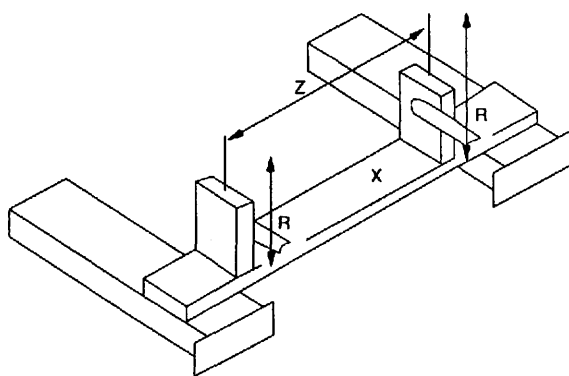
9 - Casing

10 - Slide

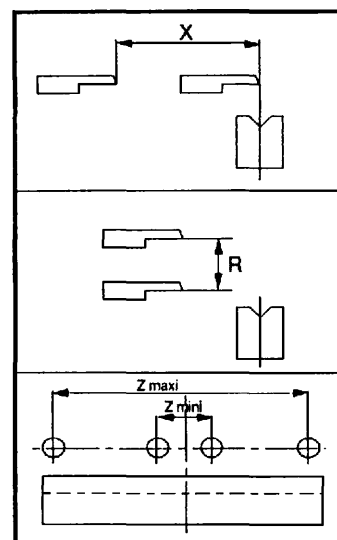
10 - 3 REAR GAUGE ASSEMBLY MECHANISM ON MODEL 600



- 1 - Slide guideplate
- 2 - Guide spindles
- 3 - Ball screw
- 4 - Motor
- 5 - Transmission system
- 6 - Inductive limit switches
- 7 - Adjustment sensor (ITPS only)
- 8 - Encoder
- 9 - Casing
- 10 - Slides



| TYPE | MACHINES EQUIPEES | | | |
|------|-------------------|-------|-----|--------|
| | 50/20 | 80/25 | 103 | 125/30 |
| 620 | • | | | |
| 625 | | • | | |
| 620 | | | • | • |



X AXIS

| GAUGE | STROKE (in mm) | SPEED (in mm/sec) | | POSITIONING ACCURACY (in mm) |
|-------|-------------------|----------------------|------|---------------------------------|
| | | ITS | ITPS | |
| 412 | 400 | | | |
| 620 | 600 | 160 | 200 | |
| 625 | 600 | ± 10 | ± 10 | |
| 630 | 600 | | | |

R1 AXIS, motor-driven R2

| GAUGE | STROKE (in mm) | SPEED (in mm/sec) | | POSITIONING ACCURACY (in mm) | |
|-------|-------------------|----------------------|------|------------------------------|-------|
| | | ITS | ITPS | ITS | ITPS |
| 412 | 130 ± 10 | | | ± 0,3 | ± 0,1 |
| 620 | | 30 | 60 | | |
| 625 | | ± 5 | ± 5 | | |
| 630 | | | | | |

* This value is also applicable to axes R1 and R2 in the manual version.

Z AXIS

| GAUGE | STROKE (in mm) | SPEED (in mm/s) | | DISTANCE BETWEEN FINGERS | | ACCURACY (in mm) |
|-------|-------------------|--------------------|----------|--------------------------|------|---------------------|
| | | ITS | ITPS | Max. | Min. | |
| 412 | 510 | | | 105 | 615 | (manual) |
| 620 | 895 | (manual) | (manual) | | 1000 | |
| 625 | 1395 | ± 150 | ± 170 | 105 | ± 1 | |
| 630 | 1815 | ± 5 | ± 10 | | 1500 | |